

HW5

165583

Try different numbers of neurons and training algorithms, compare control results.

156352

Very good analysis, but no experiments with different numbers of neurons and training algorithms

178248

No simulation scheme

163012

Very good analysis, but no experiments with different numbers of neurons and training algorithms

165694

Very good analysis, but no experiments with different numbers of neurons and training algorithms

165593

Influence of different number of neurons and different training algorithms is not analyzed

177971

Experiments on figure 3 were made with "Tank" model, not with the system that you need to control in the home task ("Jacketed CSTR"): limitation 0.3 m is clear.

The same is on page 5.

No control results shown.

165547

Very good analysis, but training algorithm and activation function are different things

165575

It can be seen from figure 2, that you are identifying a wrong system - "Tank" model, not the system that you need to control in the home task ("Jacketed CSTR").

Control doesn't work (figure 5). Oscillations are too high!

163494

No analysis. Experiments at the end of the report are not commented.

177940

No experiments with different training algorithms

165585

No experiments with different numbers of neurons and training algorithms

163216

No experiments with different numbers of neurons and training algorithms

177355

Very good analysis, but no experiments with different training algorithms

172954

Not your report (177355)

165587

One input of model B block "Add" is missing. That is why model B doesn't work. Input of the integrator is not control error, but set point.

165584

It can be seen from figure 1, that you are identifying a wrong system - "Tank" model, not the system that you need to control in the home task ("Jacketed CSTR").

Control doesn't work (last 2 figures). Oscillations are too high!

177943

It can be seen from identification figures, that you are identifying a wrong system - "Tank" model, not the system that you need to control in the home task ("Jacketed CSTR").

Control doesn't work. Oscillations are too high!

177822

It can be seen from identification figures, that you are identifying a wrong system - "Tank" model, not the system that you need to control in the home task ("Jacketed CSTR").

Control doesn't work. Oscillations are too high!

177258

It can be seen from figure 1.2, that you are identifying a wrong system - "Tank" model, not the system that you need to control in the home task ("Jacketed CSTR"). Limitation 0.3 is clear that is the case in "Tank" model. Used data set is not correct!

This is because of
load input.mat u
load output.mat y

You generated data correctly (figure 1.0), but didn't use them because of loading data from the file that we used in the class.
Control doesn't work. Oscillations are too high!

165510

No experiments with different numbers of neurons and training algorithms

178177

Control doesn't work. Output is 0.3. Most probably, you used wrong data set for training the network (loaded dataset that we used in the lab - it was in the beginning of the training file), but there is no listing in the report. So, it is not possible to say why, but the system doesn't work correctly.

165579

No experiments with different numbers of neurons and training algorithms