

ISS0031 Modeling and Identification

Exercises for Laboratory Work #2

Linear Programming

The MATLAB function

```
x = linprog(c, A, b, Aeq, beq, lb, ub)
```

solves the linear programming problem specified by

$$z = c^T x \rightarrow \min$$

subject to constraints

$$A \cdot x \leq b$$

$$A_{eq} \cdot x = b_{eq}$$

$$lb \leq x \leq ub.$$

Example 1

Consider the following linear programming problem from Lecture 2:

$$z = x_1 + 2x_2 \rightarrow \min$$

$$x_1 + x_2 \geq 1$$

$$x_1 \geq 0, x_2 \geq 0.$$

First convert $x_1 + x_2 \geq 1$ to equivalent $-x_1 - x_2 \leq -1$ and type in MATLAB

```
c = [1; 2];  
A = [-1 -1];  
b = -1;  
lb = zeros(2,1);
```

Thereafter, run the `linprog` function specifying nonexistent matrices as empty:

```
>> [x, fval] = linprog(c, A, b, [], [], lb)  
Optimization terminated.
```

```
x =  
    1.0000  
    0.0000
```

```
fval =  
    1.0000
```

Thus, the minimum $z_{min}(1, 0) = 1$ is obtained.

Example 2

$$\begin{aligned}z &= 3x_1 + 4x_2 \rightarrow \max \\2x_1 + 4x_2 &\leq 120 \\2x_1 + 2x_2 &\leq 80 \\x_1 \geq 0, x_2 &\geq 0.\end{aligned}$$

This is a problem of maximization. To use MATLAB to solve it we need to convert the objective function as follows:

$$z' = -3x_1 - 4x_2 \rightarrow \min,$$

where $z' = -z$. Now, construct the matrices c, A, b , and lb and solve this problem.

Individual Exercises

1. Solve the problem from today's lecture:

$$\begin{aligned}z &= 4x_1 + 3x_2 \rightarrow \max \\3x_1 + x_2 &\leq 9 \\-x_1 + x_2 &\leq 1 \\x_1 + x_2 &\leq 6 \\x_1 \geq 0, x_2 &\geq 0.\end{aligned}$$

2. Learn to use the `optimtool` optimization tool and use it to solve the above problems.

Nelder-Mead Simplex Method

Use the supplied `optimize` function to locate the minima of the following functions.

- **Rosenbrock function**

$$f_R(x_1, x_2) = (1 - x_1)^2 + 100(x_2 - x_1^2)^2.$$

- **Himmelblau's function**

$$f_H(x_1, x_2) = (x_1^2 + x_2 - 11)^2 + (x_1 + x_2^2 - 7)^2.$$

This function has several minima. Locate them by means of

- Choosing different initial points in the search space;
- By using search variable bounds;
- By using constraints.

Hint: use MATLAB's anonymous function mechanism to construct the cost function that is passed to `optimize`.

Individual Exercise

Write a MATLAB script for automating the task of finding all roots of Himmelblau's function using Nelder-Mead simplex algorithm.